



The LOTUS project goals: to recent years sources of uncertainties in trend retrieval establish more suitable alternatives.

SPARC website : http://www.sparc-climate.org/activities/ozone-trends/ LOTUS workshop website https://events.oma.be/indico/event/23/

Satellite datasets per measurement principle	
Group 1. Ozor	ne profiles from nadir sensors (partial colun
on pressure gri	d)
SBUV MOD Re	lease 6;
SBUV Merged	Cohesive
Group 2. Ozor	he profiles from limb instruments in mixing ra
on pressure gri	d
HALUE – MILS	a profile of freme line by in other une on to the second
Group 3. OZO	ne profiles from limb instruments in num
SACE II $_$ OSIRIS:	
SAGE II – OSIRIS, $SAGE II – OSIRIS – OMPS'$	
SAGE II – Ozone, cci – OMPS	
The dataset with converted ozone representation	
Mixed coordinates converted to mixing ratio on pressure	
GOZCARDS	
Instrument	Station, period since
Lidar	OHP (1986), Hohenpeißenberg (1987), Tab Mountain (1988), Mauna Loa (1993), Laude (1994)
Microwave	Bern (1994), Payerne (2000), Mauna Loa(1995), Lauder (1992)
FTIR	Izana (1999), Lauder (2001), Jungfraujoch (1995), Wollongong (1996)
Umkehr	Mauna Loa (1984), Lauder (1987), Arosa (1956), OHP(1984), Boulder(1984), Fairbanks (1994), Perth (1984)
Ozonesondes	NOAA and SHADOZ datasets



Overview of the Long-term Ozone Trends and Uncertainties in the Stratosphere (LOTUS) SPARC activity.

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through the different stages of analysis chain (d) Re-evaluate current best practice(s) and possibly







Figure 4. (far left). Trends derived from SBUV MOD ozone profile data averaged over 35N-50N (GAMM model). (4 panels) Common dataset test used in 8 regression models: Differences in derived Trends, Solar cycle, QBO and ENSO

Provide results of trend analyses for Chapter 3 in the WMO Ozone assessment 2018 Incorporate data uncertainties in trend estimates Write the Report on LOTUS findings

